HITBOT

Z-Arm S622

Product Brochure

The most affordable or nothing.

Main category: Industrial robot arm/Collaborative robot arm/Electric gripper/Intelligent actuator/ Automation solutions

Huiling-tech Robotic Co.,Ltd.

Z-Arm S622

Space optimization

Easy to operate

Lightweight and flexible

Cost-effective

Control Box

Button Box

Cover All the Bases

Easy to operate

Drag teaching and graphical programming effectively reduce the application threshold and time cost, and the PC interface is convenient and easy to operate.

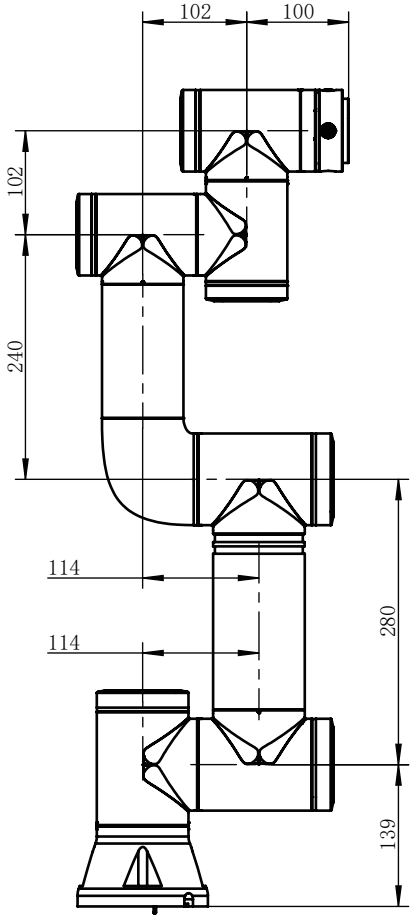
Highly integrated

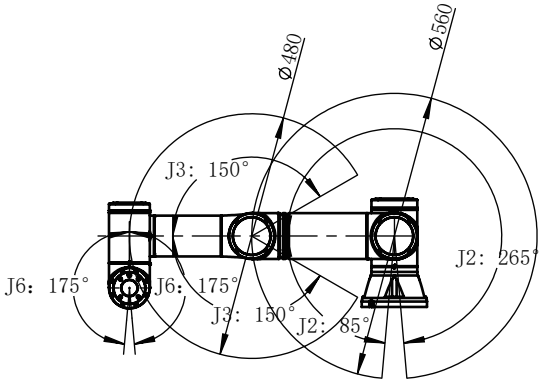
The reducer, motor, encoder and drive control are integrated for quick disassembly and assembly.

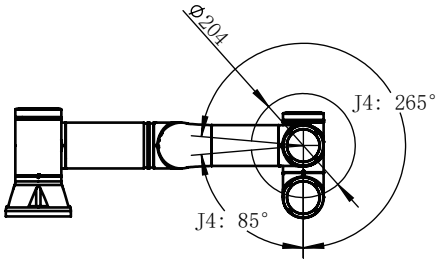
Wide range of application

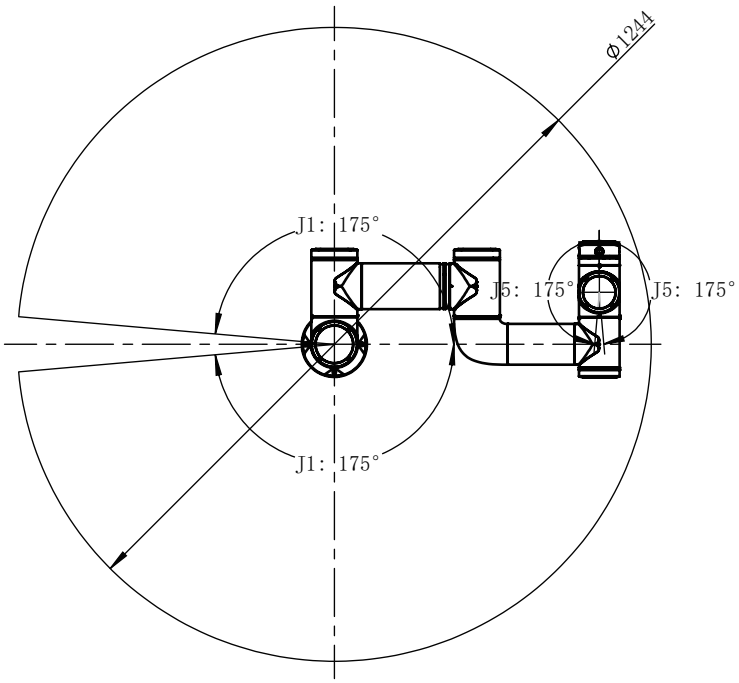
It can be used in the automotive industry, electronics industry, food and beverage industry, health care and laboratory research fields, etc.; it can meet various functional requirements such as assembly, pick and place, twist screws, dispensing, etc..

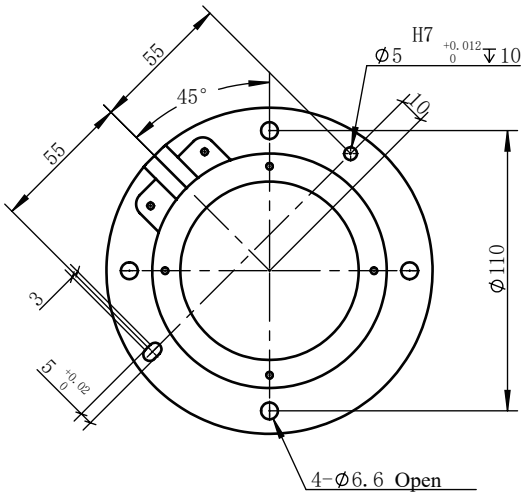
Range of Motion and Size

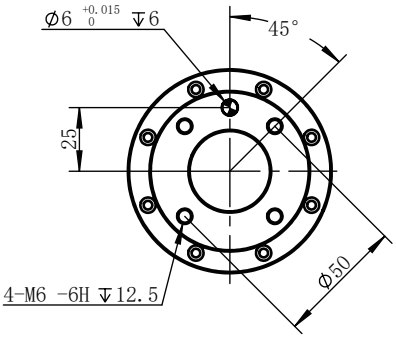


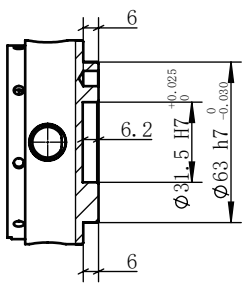








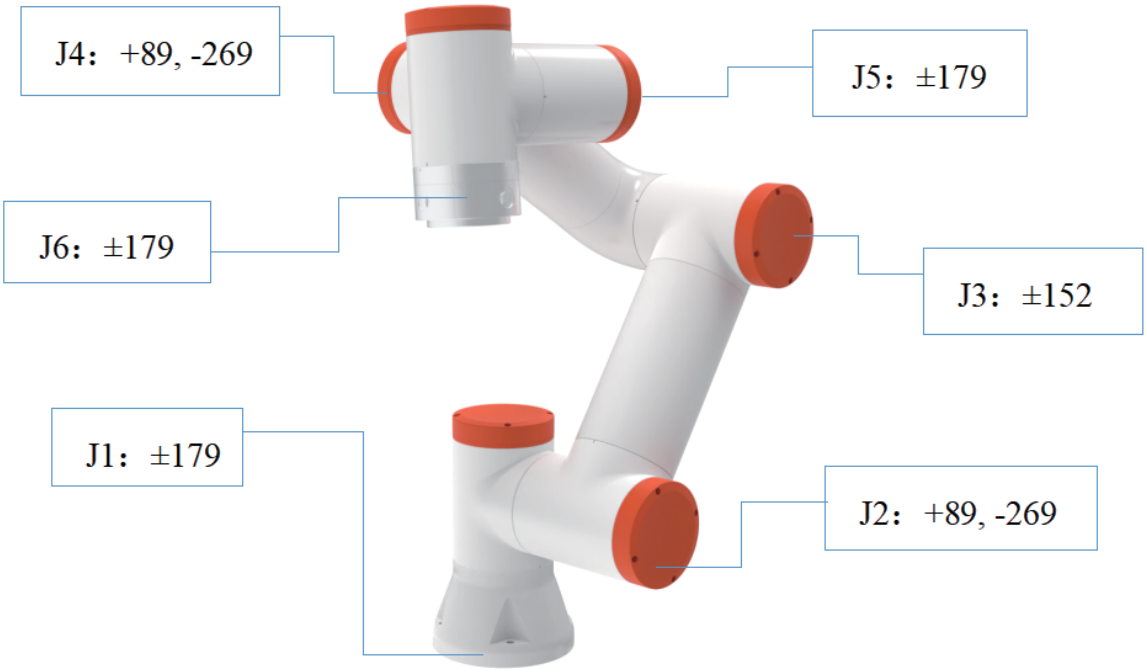




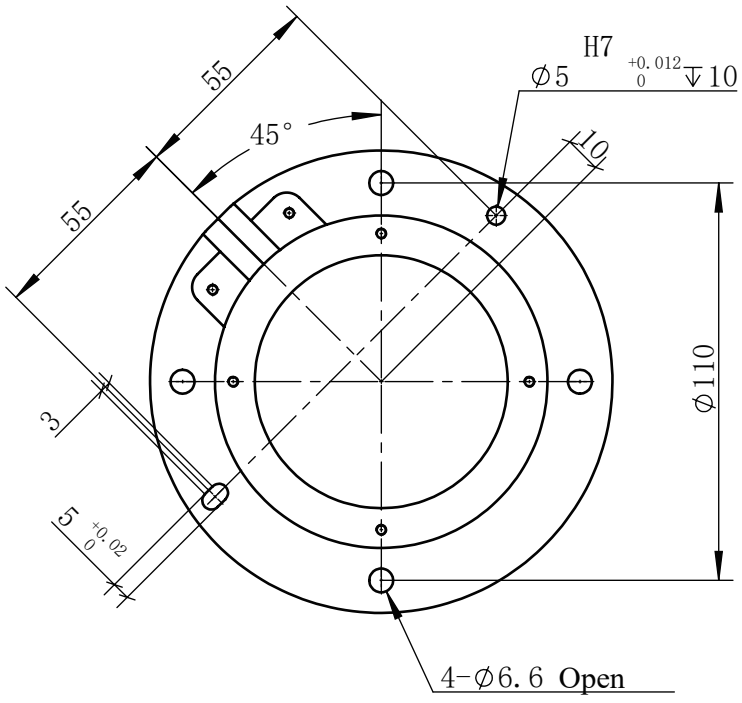
Specifications

Z-Arm S622 Collaborative Robot Arm	Parameter
Weight	≈15kg
Payload	3kg
Working Range	622mm
Joint Range of Motion Software Limit Limitation	Axis 1：±175° Axis 2：+85°，-265° Axis 3：±150° Axis 4：+85°，-265° Axis 5：±175° Axis 6：±175°
Maximum Joint Speed	180°/s
Repeatability	±0.02mm
Installation Area	φ130mm
Control Box Size	342*260*90mm（Without protrusion）
Degree of Freedom	6
End I/O Port	Digital input：2 Digital outpu：2 Analog input：1 Analog outpu：1
Control Box I/O Port	Digital input：16 Digital outpu：16 Analog input：2 Analog outpu：2
I/O Power Supply	24V/1.5A
Communication	Ethernet、TCP/IP、485communication
Noise	＜65dB
Protection Level	IP54
Coordinated Operation	With collision detection function, allowing custom collision levels
Power Supply	220V/50HZ
Use Environment	·Away from vibrations and the vibration intensity is not higher than 0.5G ·Away from corrosive gases, liquids and explosive gases ·Avoid dust, smoke and water ·Avoid equipment working under unstable current conditions
Humidity	20-80RH No condensation
Temperature	0-45℃

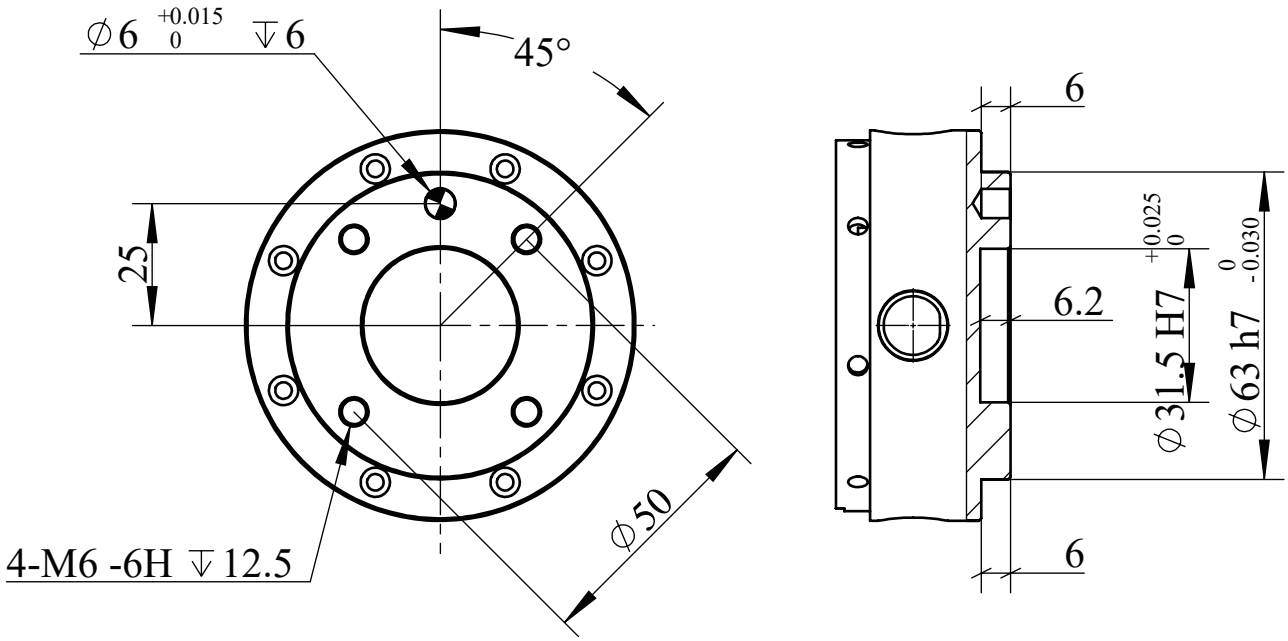
Robot Mechanical Limits



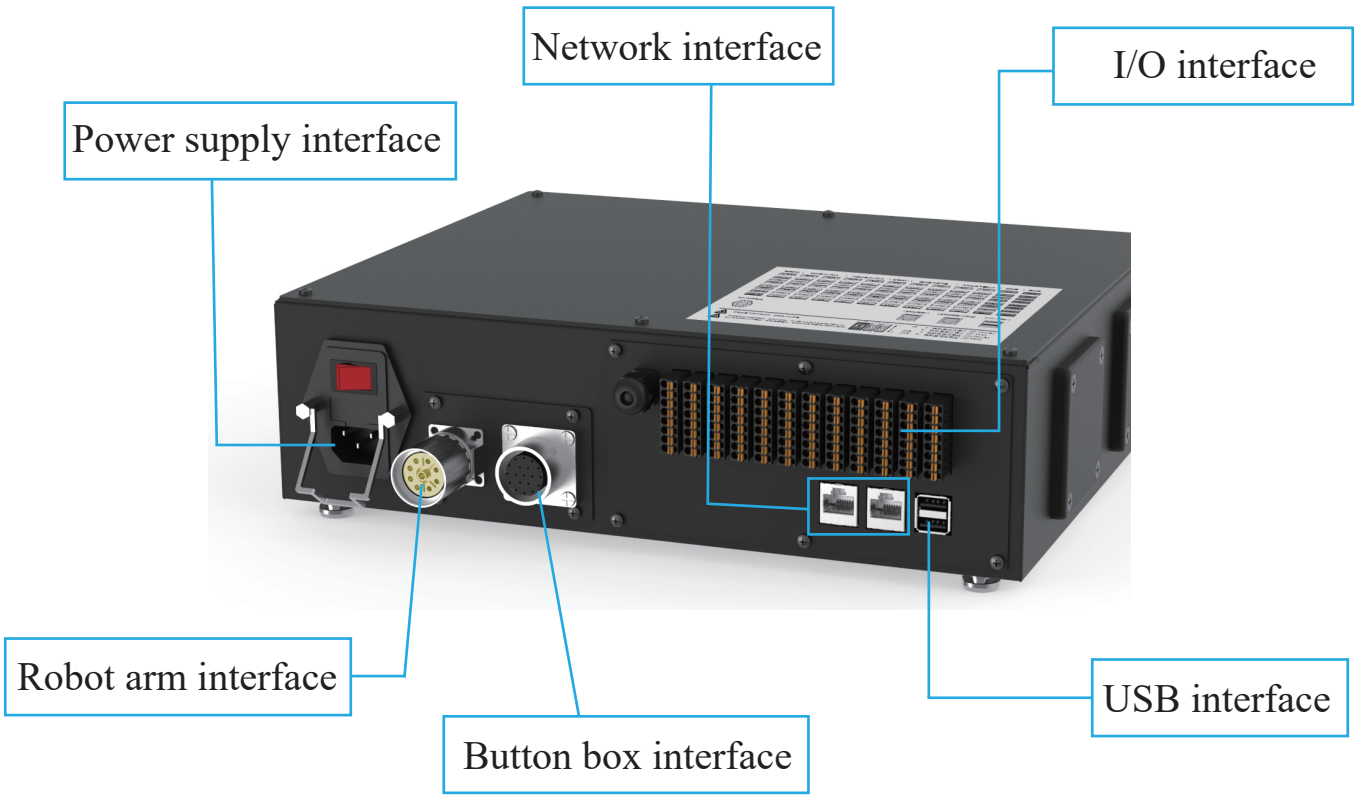
Robot Installation Dimensions



Flange Size at the End of the Robot



Control Box Wiring Panel



Controller I/O Panel

The I/O inside the control box can be used to control a variety of devices, including pneumatic relays, PLCs, and emergency stop buttons. Figure 1 shows the electrical interface group inside the control box and the network interface group of the control box.

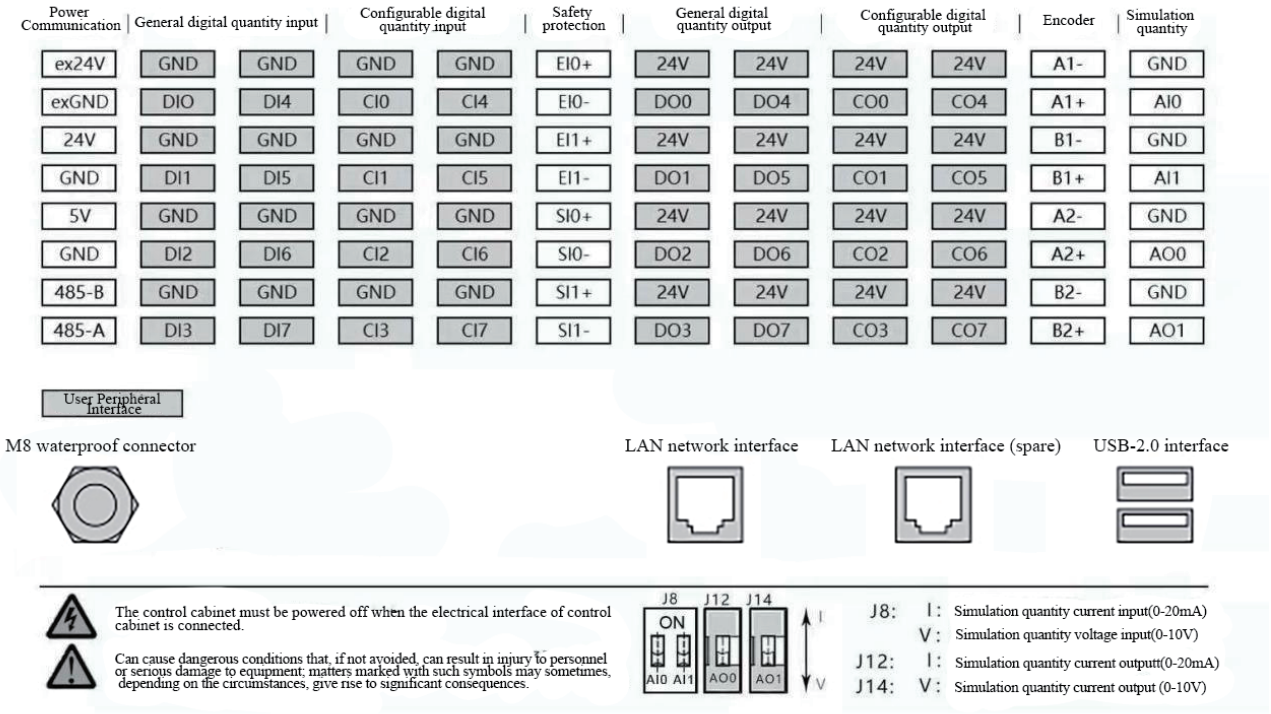


Figure 1 Control box electrical interface diagram

End Boards

The I/O and 485 communication interfaces of the end board can be used to control various devices, including pneumatic relays, PLCs and emergency stop pushbuttons.Pin distribution and pin description are shown in Figure 2. the I/O connector type is M12 connector 8-pole female.

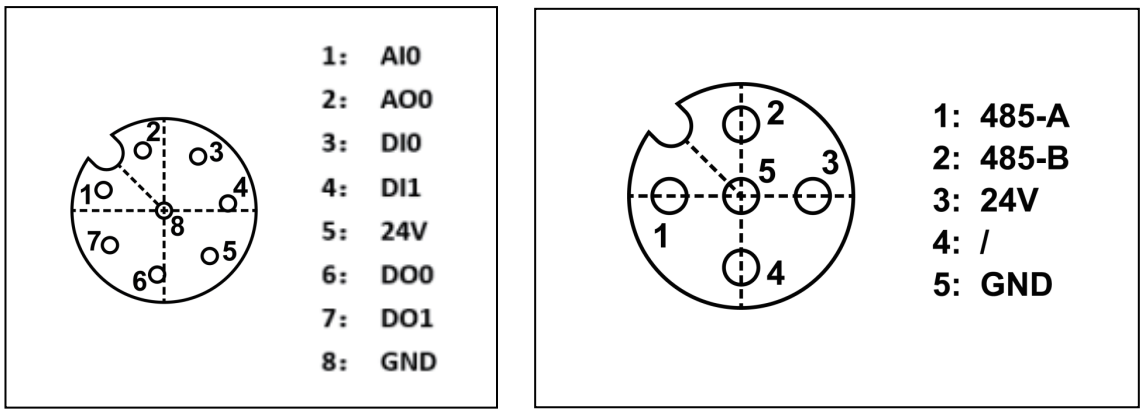


Figure 2 Schematic diagram of the electrical interface of the end version

RJ45 Network Interface Group

The network interface group address inside the control box is shown in Figure 3. Note that this figure corresponds to the order of the internal network port address of the control box, and the robot's default port is forbidden to plug and unplug. The user network port can be used to communicate with the camera and other devices, the IP address is 192.168.57.2. The button box interface is the teaching pendant control port by default, the IP address is 192.168.58.2, use the network cable to connect the button box interface and the computer,The computer's IP address is set to 192.168.58.10 or the same network segment. Open the Google browser and enter 192.168.58.2 to access the teach pendant page.

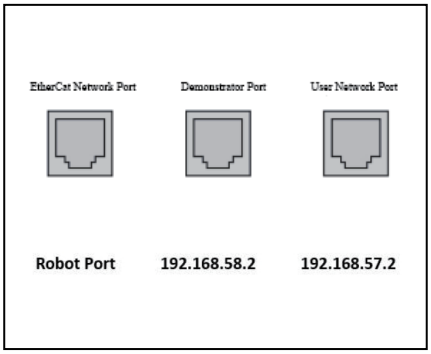


Figure 3 Schematic diagram of the network interface group

The internal and external power supplies electrical specifications are shown in the table of the internal and external electrical specifications:

Terminal	Parameter	Min. value	Typical value	Maximum value	Unit
Internal 24V power supply					
[ex24V – exGND]	Voltage	23	24	25	V
[ex24V – exGND]	Current	0	-	2	A
Internal 24V power supply					
[24V – GND]	Voltage	23	24	25	V
[24V – GND]	Current	0	-	1.5	A

The digital I/O electrical specifications are shown in the table of the digital I/O electrical specifications:

Terminal	Parameter	Min. value	Typical value	Maximum value	Unit
Digital output					
[COx / DOx]	Current	0	-	1	A
[COx / DOx]	Voltage Drop	0	-	0.5	V
[COx / DOx]	Leakage current	0	-	0.1	mA
[COx / DOx]	Function	-	NPN	-	Type
Digital input					
[EIx/SIx/CIx/DIx]	OFF	-3	-	5	V
[EIx/SIx/CIx/DIx]	ON	11	-	30	V
[EIx/SIx/CIx/DIx]	Current (11-30V)	2	-	15	mA
[EIx/SIx/CIx/DIx]	Function	-	NPN	-	Type

Analog I/O specifications are shown in the table of the analog current and voltage specifications.

Terminal	Parameter	Min. value	Min. value	Maximum value	Unit
Analog current input					
[AIx - END]	Current	0	-	20	mA
[AIx - END]	Impedance	-	500	-	ohm
[AIx - END]	Resolution	-	12	-	bit
Analog voltage input					
[Alx - END]	Current	0	-	10	V
[Alx - END]	Impedance	-	510	-	Kohm
[Alx - END]	Resolution	-	12	-	bit
Analog current output					
[AOx - END]	Current	0	-	20	mA
[AOx - END]	Voltage	0	-	10	V
[AOx - END]	Resolution	-	12	-	bit
Analog voltage output					
[AOx - END]	Voltage	0	-	10	V
[AOx - END]	Current	0	-	20	mA
[AOx - END]	Impedance	-	100	-	ohm
[AOx - END]	Resolution	-	12	-	bit

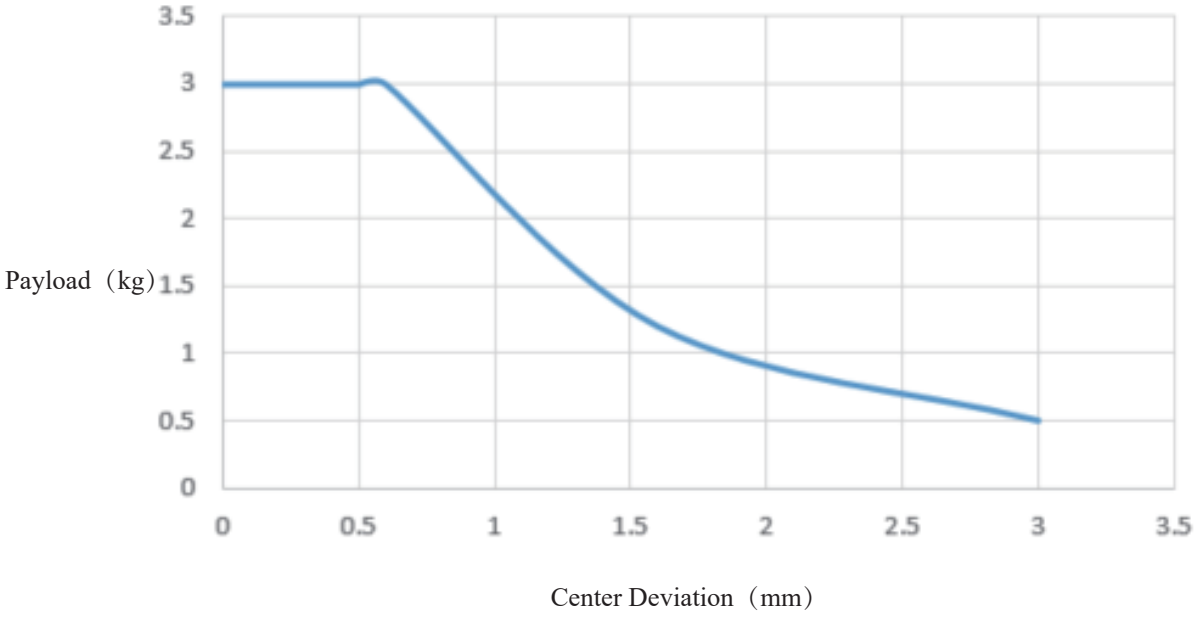
Installation Environment

When installing and using the collaborative robots, make sure that the following requirements are met.
·Ambient temperature 0-45℃
·Humidity 20-80RH without condensation
· Keep away from vibration, and the intensity of vibration is not higher than 0.5G
·Keep away from corrosive gas, liquid and explosive gas
·Avoid dust, smoke and water
·Avoid equipment working under unstable current conditions

Caution:
Please contact us if you want to hoist or install the collaborative robot on a vertical surface.

Max. Payload

The maximum allowable payload of the robot arm depends on the offset of the center of gravity. The maximum load of 3kg is the load value at the center of gravity 30mm from the center of the end. When the distance from the center of gravity of the load becomes farther, the load on the robot will become smaller.



Recommended terminal I/O connector: M12 five-pin and eight-pin aviation plug, 20~26AWG, PG7 (4-6mm), -40~+85℃
Adaptable grippers: EFG-FS/EFG-L/EFG-R/EFG-20 NM/EFG-100

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